

# Asymmetric prediction intervals using half moment of distribution

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# Motivation

- Defining safety stock level is important in inventory control.
- The safety stock calculation is connected to the calculation of Prediction Intervals (PI):
  - ▶ one vs. two-sided  $\alpha$ ;
  - ▶ cumulative vs. per-period.
- Typically we assume symmetric error distributions  $\rightarrow$  often inappropriate.
- Develop (relatively) simple ways to produce asymmetric PIs.



# How are PIs typically constructed?

- We calculate PIs as:

$$\mu_{t+h|t} - z_{\alpha/2}\sigma_{t+h|t} < y_{t+h} < \mu_{t+h|t} + z_{1-\alpha/2}\sigma_{t+h|t}, \quad (1)$$

- ▶  $\mu_{t+h|t}$  is the conditional mean,
  - ▶  $\sigma_{t+h|t}$  is the conditional variance,
  - ▶  $z_{1-\alpha/2}$  is the z-statistic value for probability  $\alpha$ .
- Assuming normality  $z_{1-\alpha/2} = \Phi^{-1}(1 - \alpha/2)$
  - Eq. (1) is also a good approximation for cases of not normal, but **symmetric** distributions.



# What should we do when the distribution is not symmetric?

- We want to use information about asymmetry, in a relatively simple way → easy to transfer to practice.
- Idea:
  - ▶ use different estimation of lower and upper variance differently
  - ▶ use different statistics → standard deviation makes sense when the distribution is symmetric and  $\bar{Y}$  describes well the central tendency of the error distribution.
- We introduce a statistic that does both, the **half moment**.



## Half moment and its properties

- Half moment measures density of distribution on left and right sides from some constant  $C$ , which is a measure of central tendency:

$$\text{HM} = \sum_{t=1}^T \sqrt{y_t - C},$$

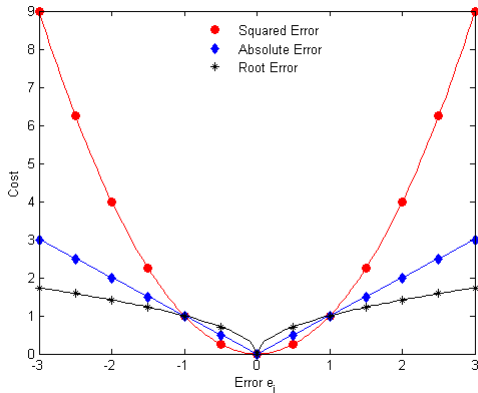
- ▶  $y_t$  is variable of interest.
- HM is in general a complex number:

$$\text{HM} = \Re(\text{HM}) + i\Im(\text{HM})$$

- $i$  is imaginary unit that satisfies:  $i^2 = -1$ .



## HM is robust to extreme values



- Real part  $\Re(\text{HM})$  determines density of right-hand side (from  $C$ ) of distribution  $\rightarrow$  that would be errors above the centre.
- Imaginary part  $\Im(\text{HM})$  shows density of left-hand side of distribution  $\rightarrow$  that would be errors below the centre.
- The higher values of  $\Re(\text{HM})$  or  $\Im(\text{HM})$  are, the longer corresponding tail of distribution is.
- Note that  $\Re(\text{HM})$  and  $\Im(\text{HM})$  do not have to be equal.
- If the size of the real and imaginary parts is the focus then the **Half Absolute Moment** (HAM) is connected to HM:

$$\text{HAM} = \sum_{t=1}^T \sqrt{|y_t - C|} = \Re(\text{HM}) + \Im(\text{HM}).$$



- HM for standard normal distribution is:

$$\text{HM}_N = (1 + i)\Gamma(0.75)\pi^{-0.5}2^{-0.75} \approx (1 + i)0.411,$$

- ▶  $\Gamma(\cdot)$  is Gamma function.

- Bounds can be constructed using this information:

$$\begin{cases} \mu_{t+h|t} + z_{\alpha/2} \Im(\text{HM}_{t+h|t})^2 / \Im(\text{HM}_N)^2 \\ \mu_{t+h|t} + z_{1-\alpha/2} \Re(\text{HM}_{t+h|t})^2 / \Re(\text{HM}_N)^2 \end{cases},$$

- so  $\Im(\text{HM})^2 / \Im(\text{HM}_N)^2$  is estimate of  $\sigma_l$  for left-hand side, while  $\Re(\text{HM})^2 / \Re(\text{HM}_N)^2$  is estimate of  $\sigma_r$  for right-hand side.





- For standard deviation  $C$  is  $\bar{Y}$
- The question is how to estimate  $C$  for HM (or HAM). This can be:
  - ▶ Mean of  $y_t \rightarrow$  assumes symmetry;
  - ▶ Median of  $y_t \rightarrow$  robust to extremes, but still enjoys symmetry;
  - ▶ Mode of  $y_t \rightarrow$  does not assume symmetry, but needs to be estimated;
  - ▶ Optimal value based on minimum of HAM:

$$C = \operatorname{argmin}_{c \in \mathbb{R}} \sum \sqrt{|y_t - c|}$$



## A standard deviation based alternative

- Another way of constructing asymmetric PI  $\rightarrow$  estimate  $\sigma_l$  and  $\sigma_r$  separately:

$$\sigma_l = \frac{1}{T_l} \sum_{y_t < \mu} (y_t - \mu)^2$$

$$\sigma_r = \frac{1}{T_r} \sum_{y_t > \mu} (y_t - \mu)^2,$$

- ▶  $T_l$  is number of observations to the left of  $\mu$ ;
  - ▶  $T_r$  is number of observation to the right of  $\mu$ .
- Update the calculation of PIs:

$$\mu_{t+h|t} + z_{\alpha/2} \sigma_{l,t+h|t} < y_{t+h} < \mu_{t+h|t} + z_{1-\alpha/2} \sigma_{r,t+h|t}. \quad (2)$$



# Simulations

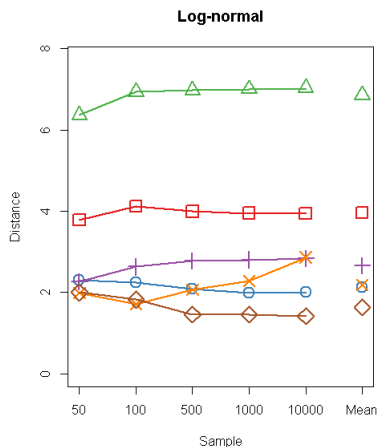
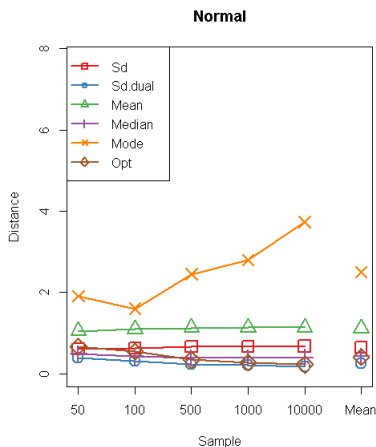
- In order to compare all the methods, we do simulations  
→ control distributions.
- 1000 samples from **Normal** and **Log-normal** distributions with sizes:
  - ▶ 50,
  - ▶ 100,
  - ▶ 500,
  - ▶ 1000,
  - ▶ 10000.
- We expect to see the proposed methods to make a difference for the Log-normal case.



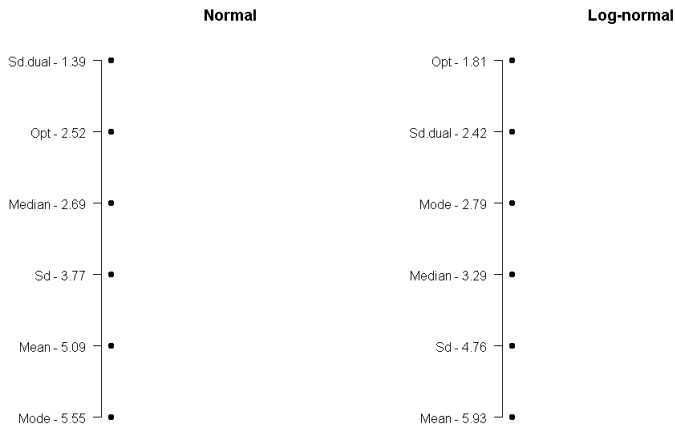
- Several PI construction methods:
  - ▶ Standard (Sd) – *benchmark*;
  - ▶ Two standard deviations, method (2) (Sd.dual);
  - ▶ HM with  $C = \bar{y}$  (Mean);
  - ▶ HM with  $C = \text{Md}(y)$  (Median);
  - ▶ HM with  $C = \text{Mo}(y)$  (Mode);
  - ▶ HM with optimised  $C$  (Opt);
- Typical metric of performance is coverage. We do not use it as it is one-sided (does not evaluate how much more you cover!)
- Instead we will use the absolute *distance* of the PIs from the empirical realised quantiles  
→ penalises both under- and over-coverage.



# Results



## Nemenyi post-hoc test for significant differences



Of course one should keep in mind that we can increase the number of distributions until we get significance!

## Normal distribution

	Sd	Sd.dual	Mean	Median	Mode	Opt
50	0.61	<b>0.39</b>	1.05	0.49	1.91	0.67
100	0.63	<b>0.30</b>	1.09	0.44	1.60	0.55
500	0.66	<b>0.23</b>	1.13	0.39	2.45	0.34
1000	0.67	<b>0.21</b>	1.14	0.39	2.80	0.28
10000	0.68	<b>0.18</b>	1.14	0.40	3.74	0.23
Mean	0.65	<b>0.26</b>	1.11	0.42	2.50	0.41

**Table:** Overall distances for different methods. Normal distribution



## Log-normal distribution

	Sd	Sd.dual	Mean	Median	Mode	Opt
50	3.78	2.30	6.36	2.26	<b>1.99</b>	2.00
100	4.12	2.24	6.93	2.63	<b>1.71</b>	1.82
500	3.99	2.09	6.98	2.78	2.07	<b>1.45</b>
1000	3.95	2.00	7.00	2.81	2.28	<b>1.45</b>
10000	3.95	2.01	7.03	2.84	2.86	<b>1.42</b>
Mean	3.96	2.13	6.86	2.66	2.18	<b>1.63</b>

**Table:** Overall distances for different methods. Log-normal distribution

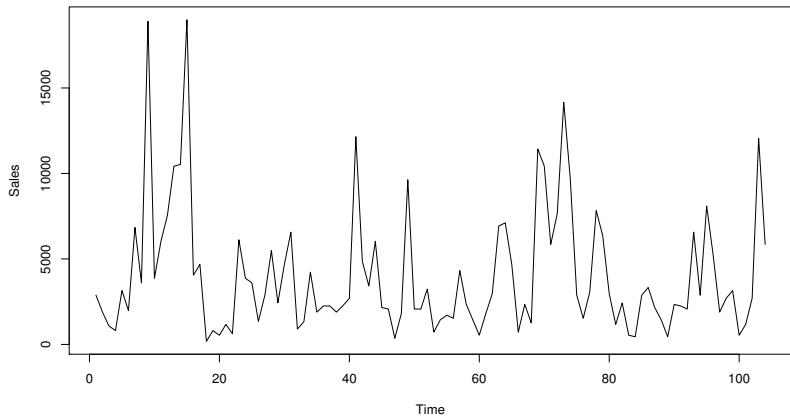




## Real data experiment

- Use 12 heavily promoted time series  
 $n = 103$  weeks, use 52 as test set.
- Perform rolling origin evaluation.
- Evaluate PI distance for one-step ahead predictions.
- Non-seasonal exponential smoothing (allow for any trend or none) with MAE as cost function  $\rightarrow$  heavily promoted.





# Results

	Dist.Lower	Dist.Upper	Dist.Total
Sd	1.93	1.93	3.85
Sd.dual	1.11	2.66	3.78
Mean	2.02	1.81	3.83
Median	1.12	1.75	2.87
Mode	<b>1.00</b>	1.79	<b>2.79</b>
Opt	1.47	<b>1.72</b>	3.19

**Table:** Overall distances for different methods.



# Conclusions

- HM produces robust asymmetric intervals;
  - ▶ is robustness desirable?
  - ▶ ... case of baseline + judgemental adjustments
  - ▶ ... shocks in the supply chain
- OK for symmetric distributions;
- It performs well error distribution is asymmetric;
- Left/right standard deviations is an interesting alternative.



# Thank you for your attention!

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